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Intelligent and Connected Vehicles—Track Testing Methods and Requirements for Automated Driving Functions

智能网联汽车 自动驾驶功能场地试验方法及要求

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1 Scope

This document specifies the general requirements, testing process, pass criteria, and test methods for automated driving functions of intelligent and connected vehicles (ICV) during track testing.

This document is applicable to Categories M and N vehicles having automated driving functions, while other vehicles may use this document as a reference.

2 Normative References

The following referenced documents are indispensable for the application of this document. For dated references, only the editions cited apply. For undated references, the latest editions of the normative document (including any amendments) apply.

GB 5768 (all parts) Road traffic signs and markings

GB 14886 Specifications for road traffic signal setting and installation

GB 14887 Road traffic signal lamps

GB/T 24720 Traffic cones GB/T 24973 Toll electric barrier

GB/T 40429 Taxonomy of driving automation for vehicles

3 Terms and Definitions

For the purposes of this document, the terms and definitions given in GB/T 40429 and the followings apply.

3.1

automated driving function

a generic term for driving automation functions of Level 3 and above as specified in GB/T 40429, including "conditionally automated driving", "highly automated driving" and "fully automated driving" functions

3.2

vehicle under test (VUT)

the vehicle subjected to the automated driving function testing

3.3

object target

the traffic participants and barriers used to construct the testing scenario

3.4

vehicle target (VT)

the passenger cars in volume production used to construct the testing scenario

3.5

automated driving mode

the mode in which the automated driving system performs all dynamic driving tasks



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